A General Phase Transition Model

Applications for vehicular traffic

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Outline

- Background and Motivation
- The Phase Transition Model
- Empirical Data Analysis
- Conclusions



- Traffic models:
 - Level of detail

Model Type	Traffic Flow Representation	Traffic Dynamics
MACro	Aggregate	Continum Models
MESo	Individual Vehicles	Continum Models
MICro	Individual Vehicles	Car-Following



- Macroscopic models
 - Assumptions:
 - Average traffic stream caracteristics
 - Continuum approximation
 - Isolated segment (no on/off-ramps)





- Macroscopic models
 - Conservation of mass (LWR equation):



 $\rho(x,t+dt)dx = \rho(x,t)dx + \left(q(\rho(x,t)) - q(\rho(x+dx,t))\right)dt$



- Fundamental Diagram
 - Relationship between density and flow:
 - Examples:
 - Greenshields





- Fundamental Diagram
 - Examples:

• Others:

• Newell–Daganzo $Q(\rho) = \begin{cases} v_f \rho & \text{if } \rho \le \rho_c \\ \frac{\rho v_f}{\rho_c - \rho_i} (\rho - \rho_j) & \text{if } \rho > \rho_c \end{cases}$

 $Q(\rho)$



- Fundamental Diagram
 - However, empirical flow density plot:
- Hysteresis in the congested branch.
- There's not a single value flow for a given density.



Previous theories:



- Based on the Colombo 2x2 phase transition model.
- In free flow: constant speed
- In congestion: introduction of perturbation q



- Formulation:
 - Conservation equations:

 $\begin{cases} \partial_t \rho + \partial_x (\rho v) = 0\\ \{\partial_t \rho + \partial_x (\rho v) = 0\\ \partial_t \rho + \partial_x (q v) = 0 \end{cases}$

if free-flow (Ω_f)

if congestion (Ω_c)

Velocity:

 $\begin{cases} v_f(\rho) = \mathbb{V} & \text{if free-flow}\left(\Omega_f\right) \\ v_c(\rho,q) = v_c(\rho,0)(1+q) & \text{if congestion}\left(\Omega_c\right) \end{cases}$

Equilibrium at q = 0

• Constraints:

• Positivity of speed: $1 + q \ge 0$

Strict hyperbolicity of the congested state: $\forall (\rho, q) \in \Omega_c \quad \rho \partial_\rho v_c(\rho, 0) + q (v_c(\rho, 0) + \rho \partial_\rho v_c(\rho, 0)) \neq 0$

Shape of Lax curves $\rho(2 \partial_{\rho} v_{c}(\rho, 0) + \rho \partial_{\rho\rho}^{2} v_{c}(\rho))$

+ $q \left(2 v_c(\rho, 0) + 4 \rho \partial_{\rho} v_c(\rho, 0) + \rho^2 \partial_{\rho\rho}^2 v_c(\rho, 0)\right)$

Implementation: Newell–Daganzo



Time space diagram







- NGSIM dataset:
 - Recorded in I-80 (video image)
 - 7 lanes (HOV+merging)
 - 30 minutes long (in congestion)
 - 0.3 miles





Trajectory data:



Eddie's generalized definitions of flow, density and speed

Density field:



CTM prediction:



CTM prediction (error field):





Conclusions

- The presented model accounts for the fact that the relation $Q(\rho)$ is not single-valued.
- Possibility of account for stop and go phenomena.
- Riemann problem solved by two different waves.
- Makes it possible to integrate density and speed measurements
- What's next: Application to NGSIM dataset.



Any questions?

Trajectory data:



Eddie's generalized definitions of flow, density and speed